EGU 2016 Accounting for surface reflectance in the derivation of vertical column densities of NO₂ from airborne imaging DOAS X2.423 AS3.9/GI2.13B222

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1. AROMAT campaign

- The AROMAT (Airborne ROmanian Measurements of Aerosols and Trace Gases) campaign was held in September 2014
- Dedicated to comparison of multiple remote sensing and in-situ instruments for satellite data validation
- Many European research institutions involved
- Two target sites
- City of Bucharest (Urban emissions from traffic and industry)
- Jiu Valley (Two large power plants with high emissions and localized plumes)
- **Shown here:** are solely measurements in the Bucharest area

2. Instrumental setup and method opening angle/FOV along track ~ 1 side lengths of pixel across trac v side length of pixel along trad aircraft single spatial pixel observed area (FOV) instantaneously observed area (iFO\ Instrumental setup The AirMAP viewing geometry Scattered sunlight from below the The swath of the push-broom imager depends aircraft is collected and fed into an on flight altitude, groundspeed of the aircraft imaging spectrometer via a sorted and exposure time. For typical values during fiber bundle (35 individual fibers), AROMAT this results in a spatial resolution of



- For the retrieval of trace gas distributions the recorded spectra are georeferenced and the DOAS method (Differential Optical Absorption Spectroscopy) is applied.
- The settings used are shown in the table to the right

Parameter	Value
Spectral calibration	Using Fraunhofer lines
Fitting window	425 – 450 nm
Trace gases	NO ₂ (298K), O ₃ (223K), O ₄ (293K), H ₂ O (HITRAN2012)
Atmospheric Effects	Ring effect (SCIATRAN calculation), constant intensity offset
Polynomial	Quadratic
Reference spectrum I ₀	Rural scene with low NO ₂
Slit function	Individual per viewing direction
AMF	SCIATRAN (see following sections)

Photographs of AirMAP

AirMAP was installed

on (Cessna 207 Turbo);

ports of entrance optics

Right: Instrument rack

carrying spectrometer,

operated by FU Berlin.

Bottom left: Nadir

and video camera

PCs, UPS etc.

Top left: Aircraft

& Aircraft :

3. Air Mass Factors

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DSCD
VCD = \frac{1}{1}
       AMF
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- The air mass factor (AMF) converts the measured differential slant column densities (DSCD) into vertical column densities (VCD)
- AMFs computed with SCIATRAN and compiled into a look-up-table with the following dependencies:
- NO₂ box profile 500m
- Surface reflectance
- Solar zenith angle
- Relative azimuth angle Viewing zenith angle
- Flight altitude



- Aerosol profile derived from AOT measurements from FUBISS-ASA2 instrument on a flight one year later on the same day of the week (Monday)
- (No measured profile available for the flight shown)

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5. Application of surface reflectance on VCD retrieval Surface reflectance derived from Compare box 3. for the assumed aerosol profile • Assuming a constant surface reflectance the VCD show clear structures colocated to bright surfaces. Applying the derived surface reflectance in the AMF yields a much smoother NO_2 field The AMF without inclusion of a variable surface reflectance shows only relatively small dependencies on viewing zenith 1.52 1.36 4 angle, solar zenith angle and relative azimuth angle

- The slope of the linear orthogonal fit is mainly determined by assumptions on the aerosol and NO₂ profile
- Depending on the viewing geometry (airborne / ground-based) aerosols above the NO₂ layer can shield the sunlight from passing though the layer (airborne) while they might enhance the NO_2 signal for the ground based system by multiple scattering processes.
- Up to now the data was evaluated independently by the different research groups, without common assumptions in the AMF computation

- Comparison to two independent co-located mobile car-DOAS measurements yields good agreement
- Comparison between car and airborne measurements can be further improved by homogenized assumptions on the aerosol and NO₂ profile
- Further analysis of the dataset to better understand the influence of aerosols on the radiative transfer



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• Generally good agreement between the mobile car-DOAS measurements and