



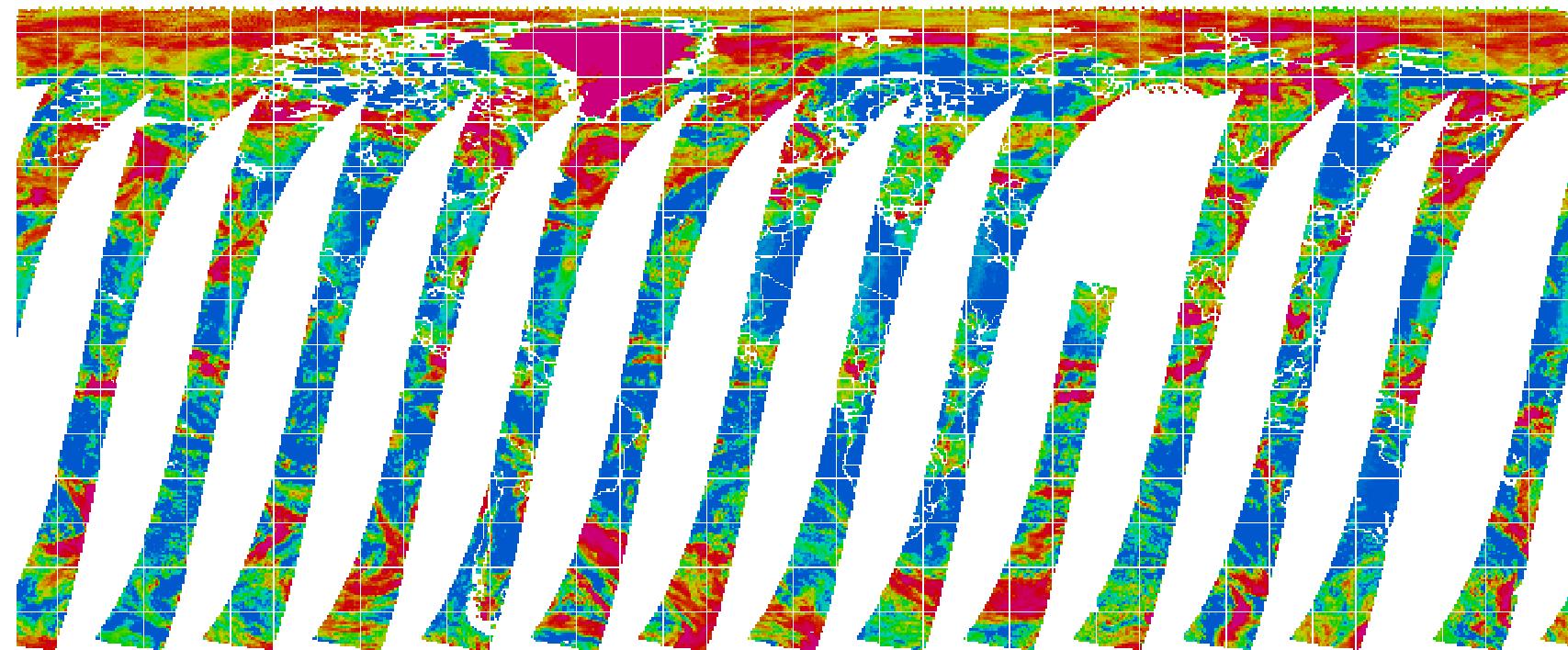
Cloud fractions and related parameters

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CRUSA 16.07.1997





Validation and further development of CRUSA

- Improvement of CRUSA and comparison with other algorithms.
- Results:
 - The outcome of CRUSA ‘s iterative fix point method are quite good background (cloud free) images
 - The values of CRUSA over ocean are inaccurate
 - (negative values, if the pixel is cloudless; too high values, if the pixel is cloudy)
 - The problems due to using the HSV-colour space.



Cloud sensitivity of the PMD-channels

- Investigation was conducted of
 - The three PMD channels (UV, green and red)
 - Sum of red channel and green channel
 - Sum of red, green and uv channel.
 - Maximum of the three channels (HSV-brightness)
 - Red-green interpolation in RGB-colour space
 - Minimum of the three PMD channels
 - Minimum of the red and the green channel.



Iterative fix point method I

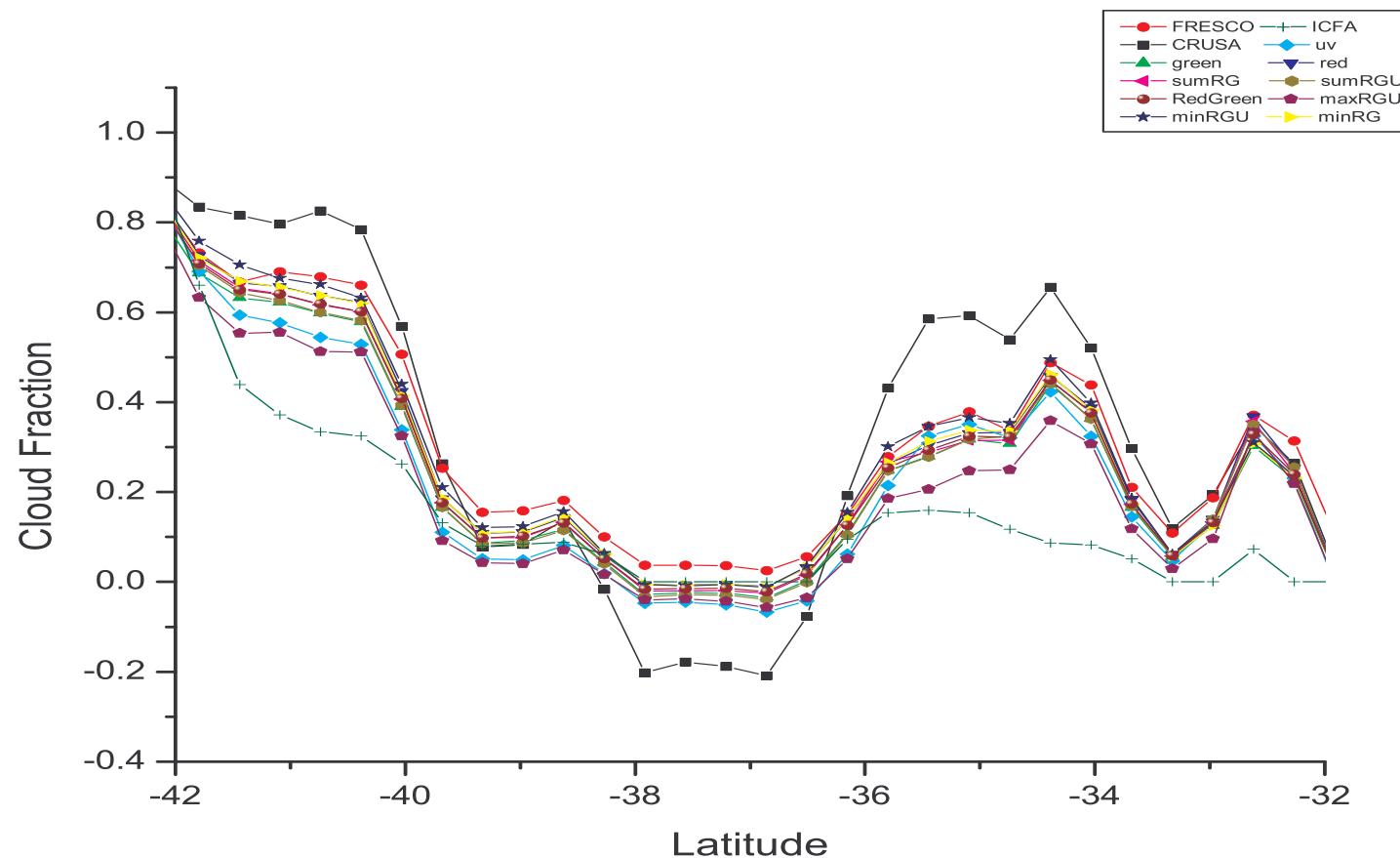
- A iterative fix point method is used to calculate background images:
 - The test was limited to data of 1997.
 - Pre-classification: cloudy pixel are removed through threshold-method. Mean of all images.
 - Cutting of clouds through comparison with the last background picture. Mean of all images.
 - The iteration ends, if there are no more changes of the background picture



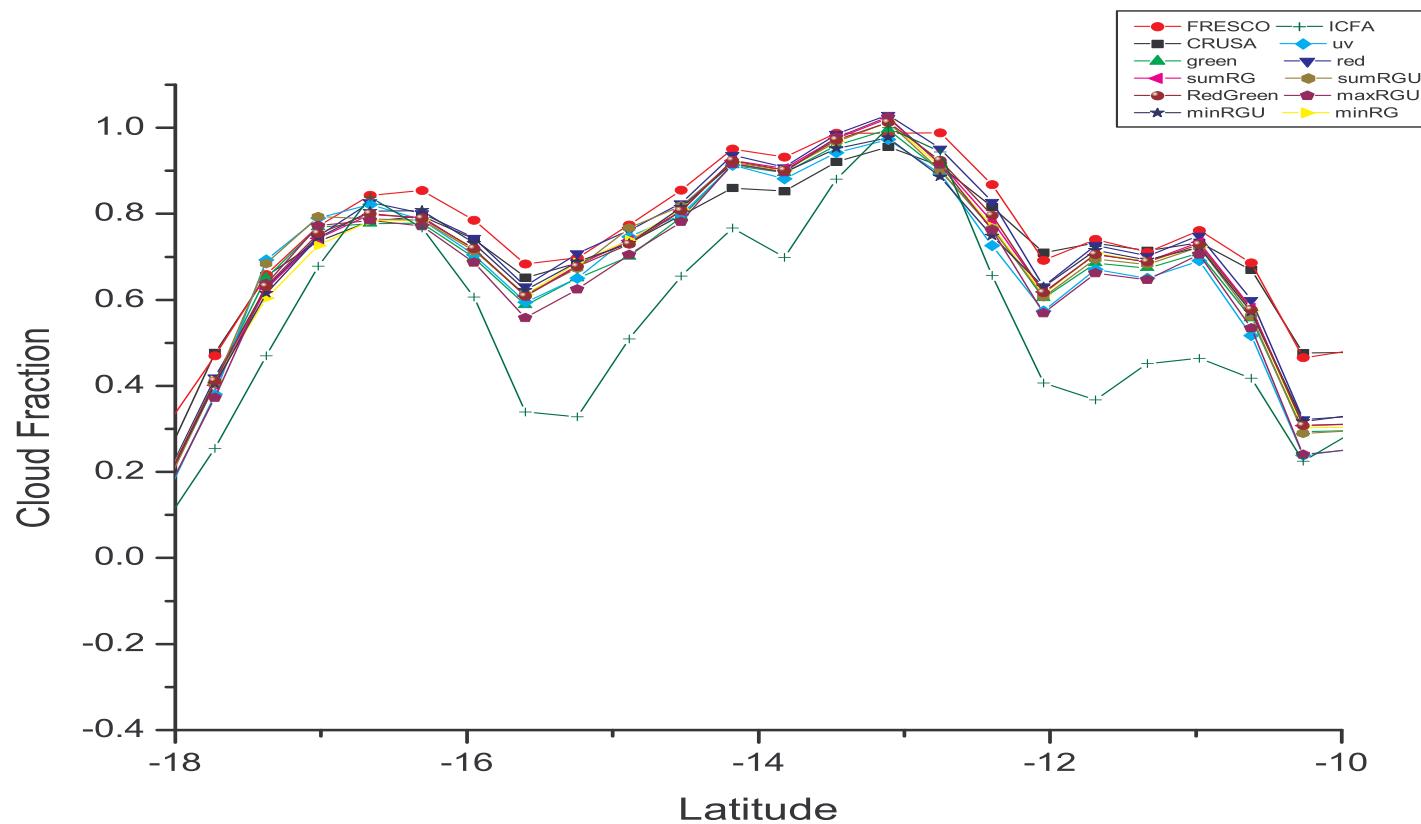
Iterative fix point method II

- We get cloud free pictures for every day:
The mean of them is the result of the iteration.
- For cloud detection the mean of the cloud free pictures of 30 days is used.
- A reference picture of maximum cloud is calculated in a similar way. Only one picture for the whole year is used.

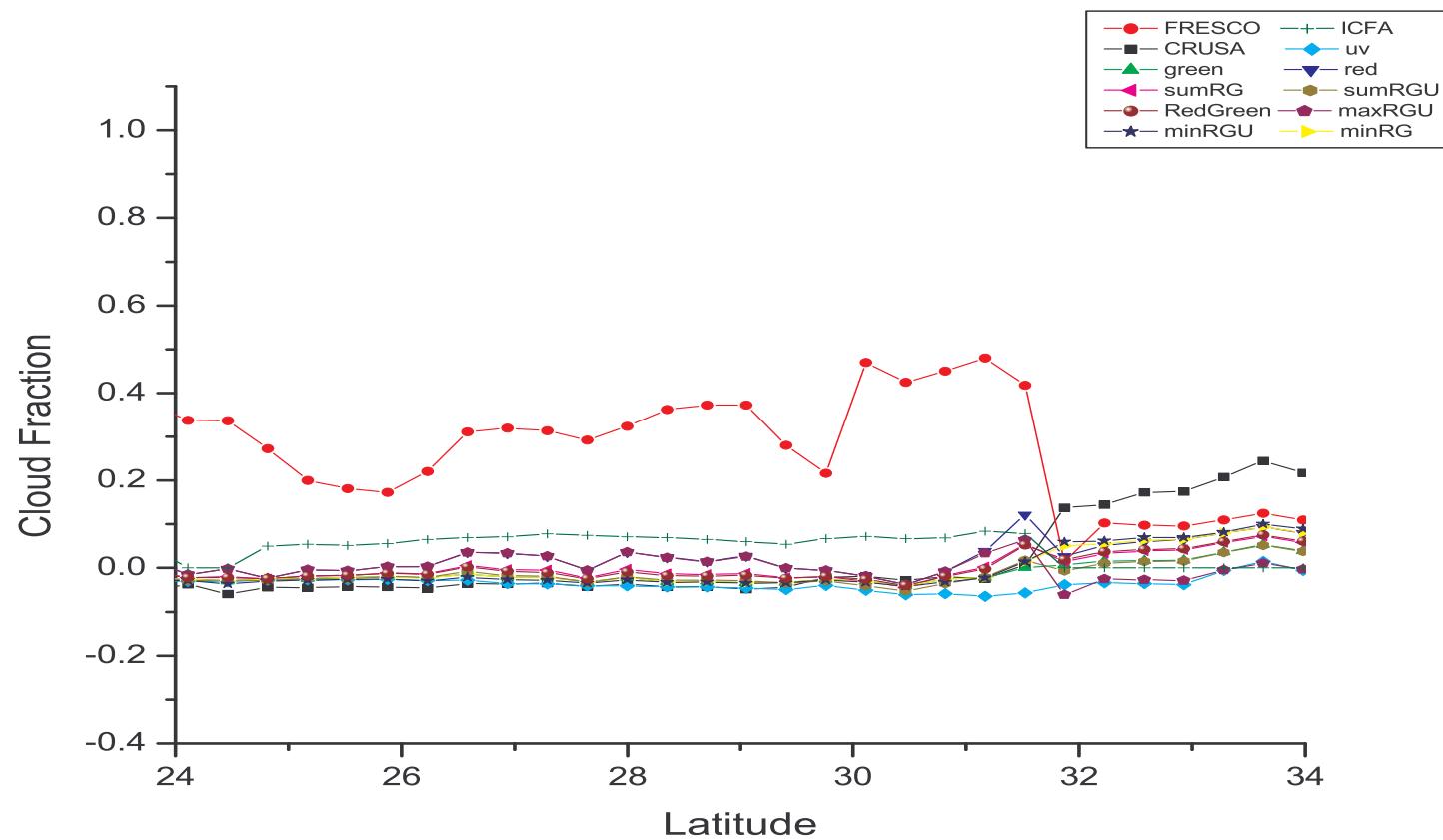
Comparison: Ocean (18.02.97)



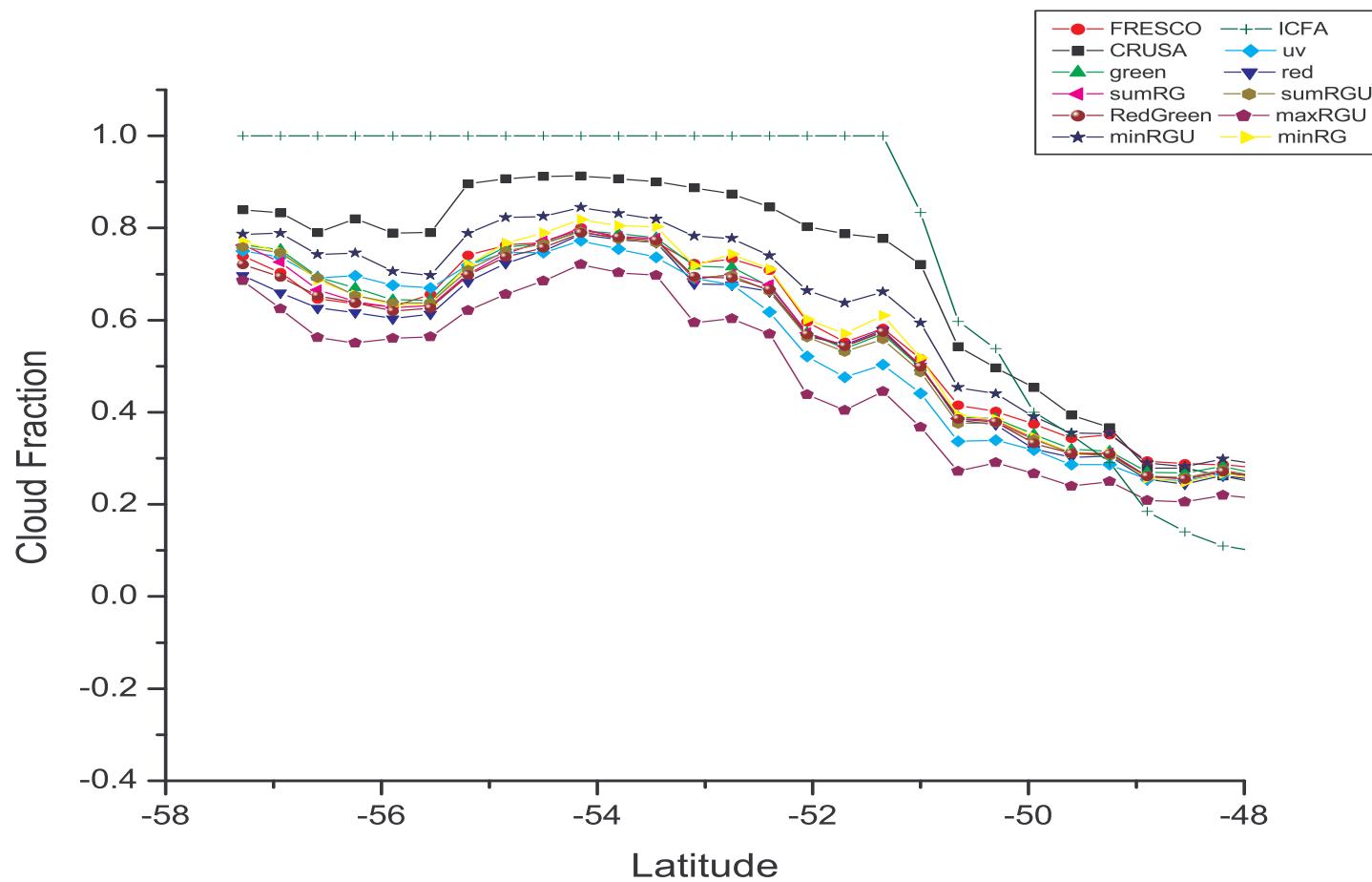
Savannah (18.02.97)



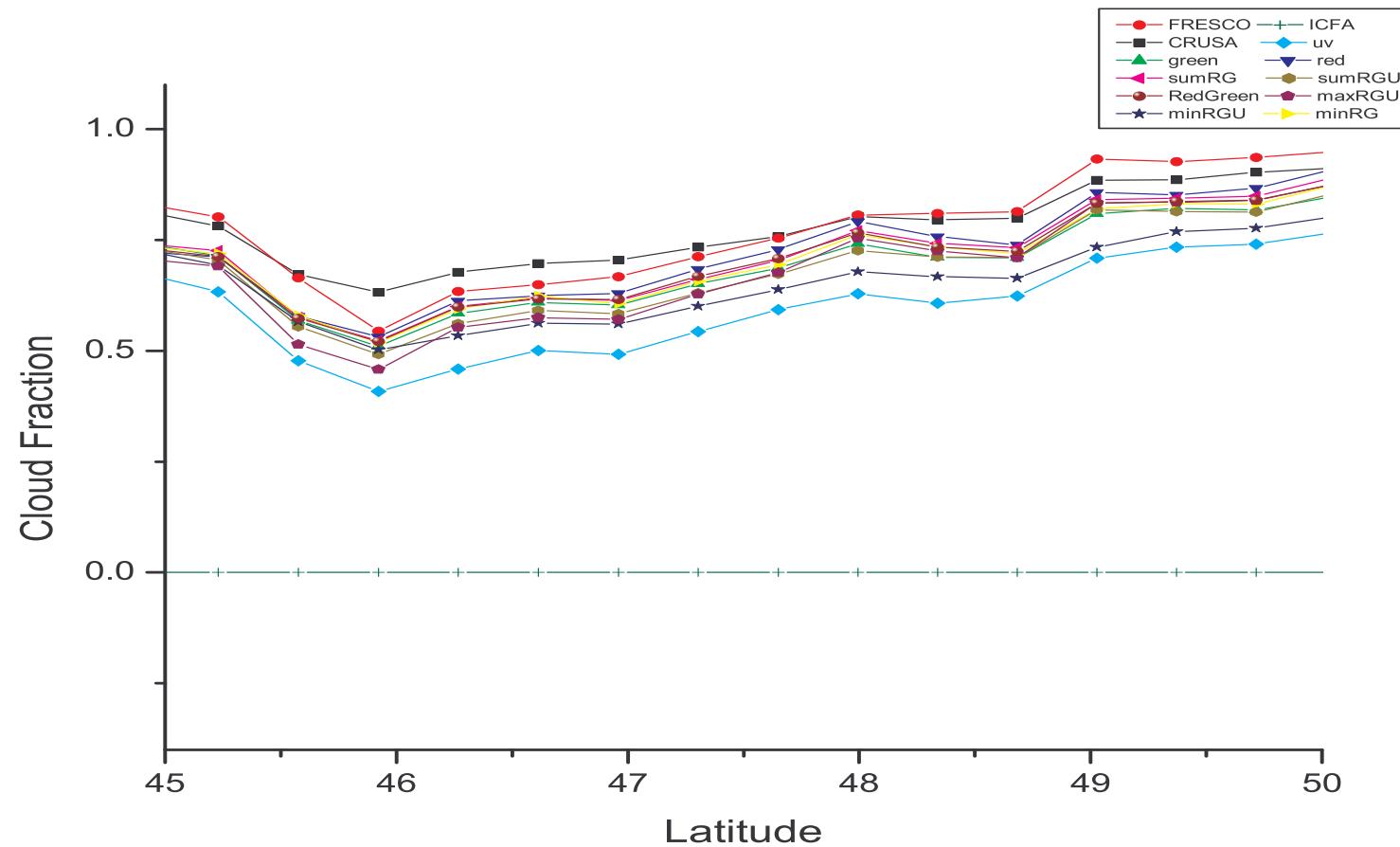
Sahara (16.07.97)



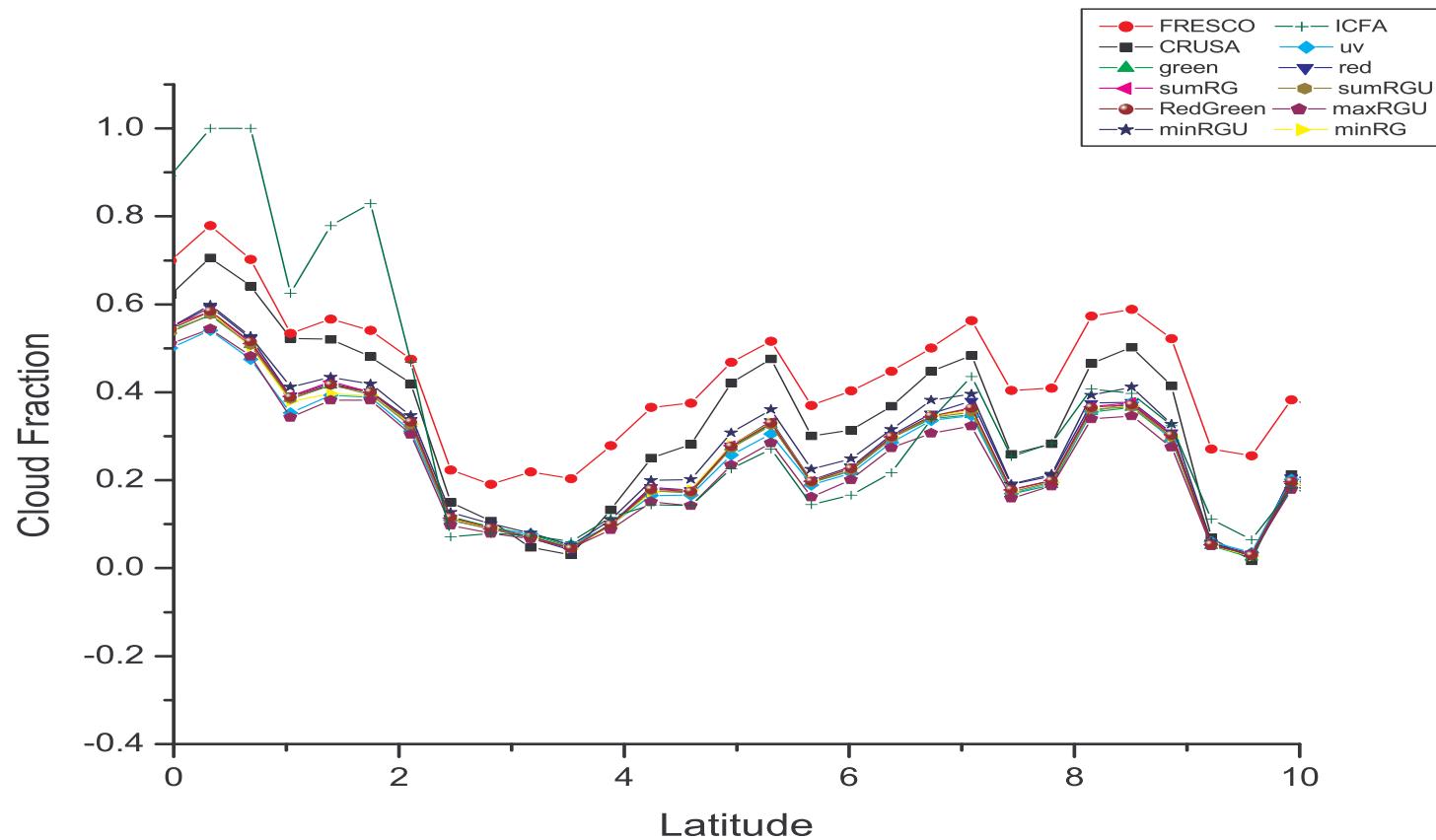
Ocean (16.07.97)



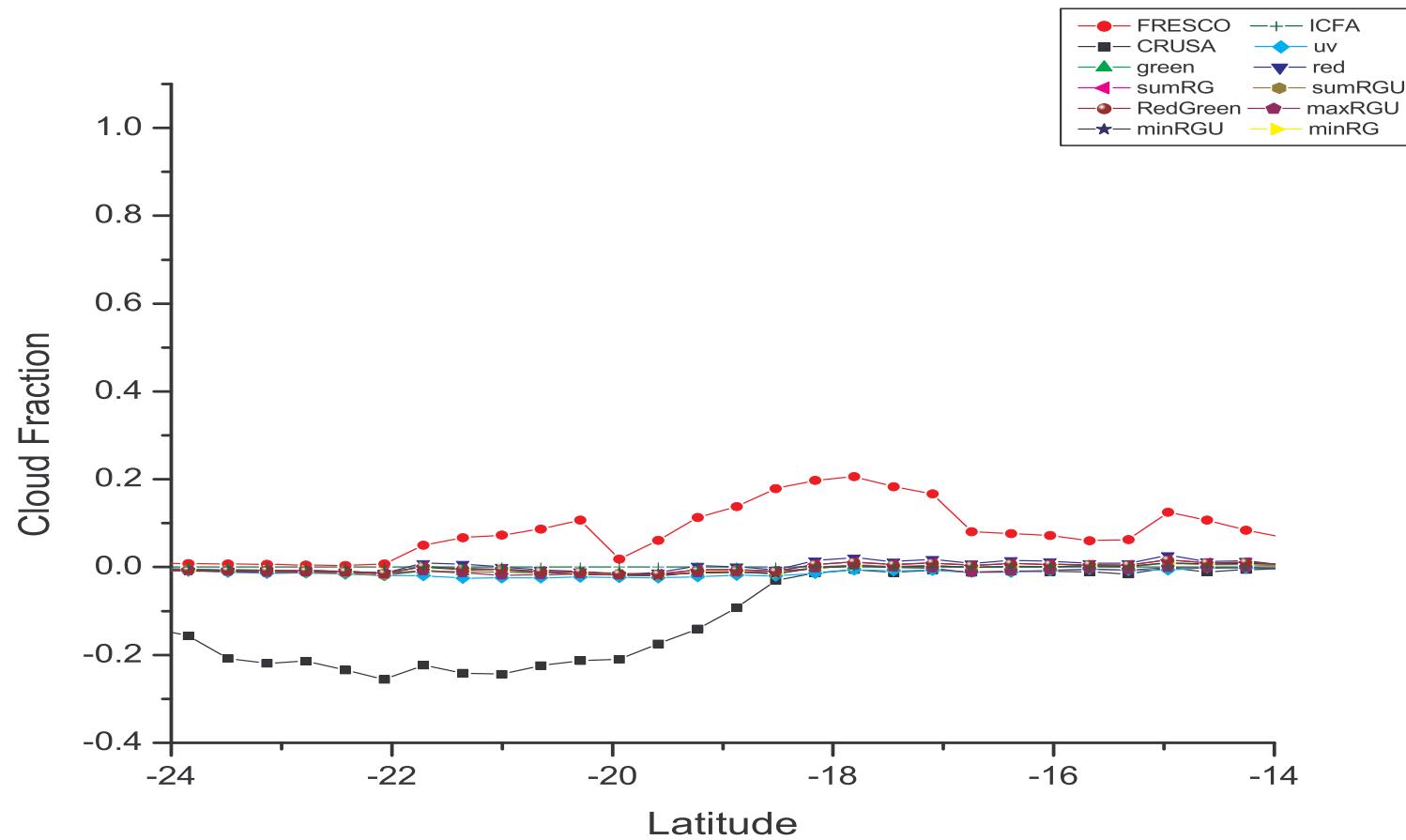
Ukraine, Black Sea (16.07.97)



Rainforest, savannah (16.07.97)



Desert and ocean (16.7.97)





Outlook I

- **Implementation of a new PMD-algorithm to detect fractional cloud cover:**
 - We won't use the UV-channel.
 - Improved background iteration:
 - Different iterations for different periods of the year using the whole GOME-Data.
 - Higher spatial resolution



Outlook II

- Improved calculation of maximum cloud
 - further investigation: determination of maximum depends only on solar zenith angle?
 - Quality of maximum cloud data depends strongly on the size of the used dataset.
- Calculation of cloud top height
 - evaluation of O₄ (630 nm), new cloud fractions and radiation transfer modelling.



The satellite group Heidelberg:

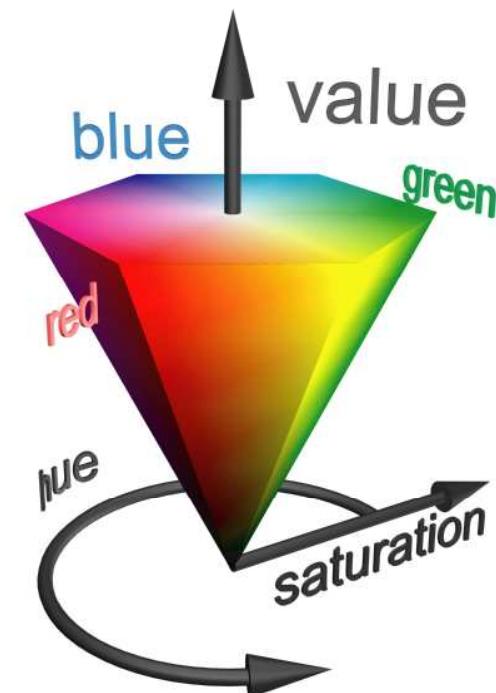
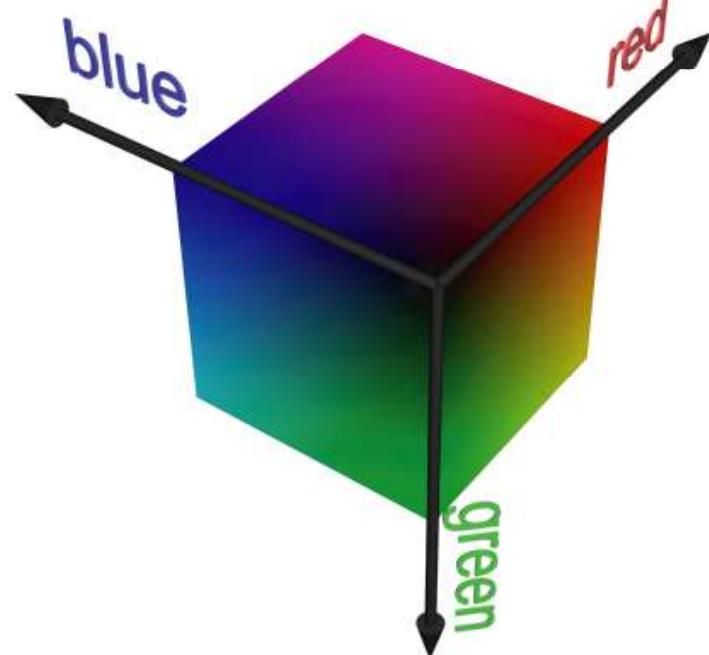
Thomas Wagner, Steffen Beirle, Nicolas Dross, Christian Frankenberg, Christoph von Friedeburg, Michael Grzegorski, Jens Hollwedel, Muhammad Fahim Khokhar, Stefan Kraus, Sven Kühl, Suniti Shangavi, Mark Wenig, Walburga Wilms-Grabe, Ulrich Platt



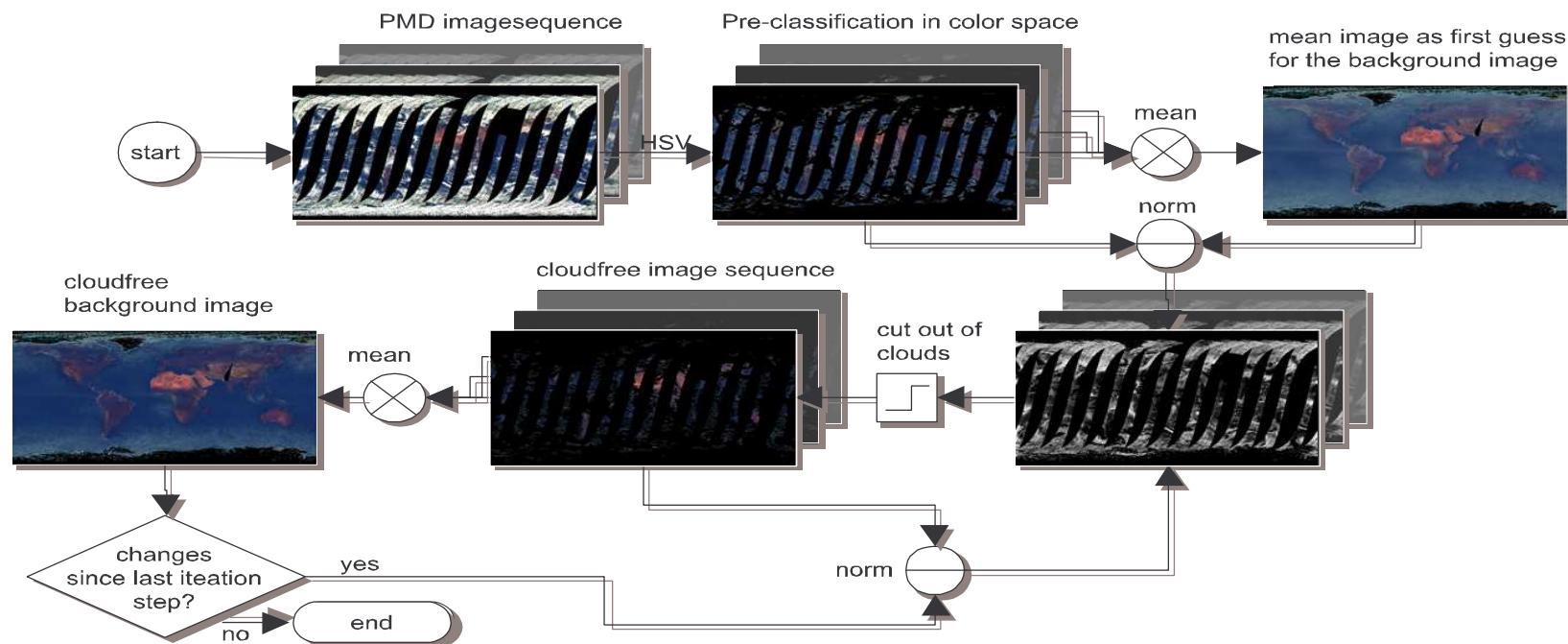


ADD-ONs

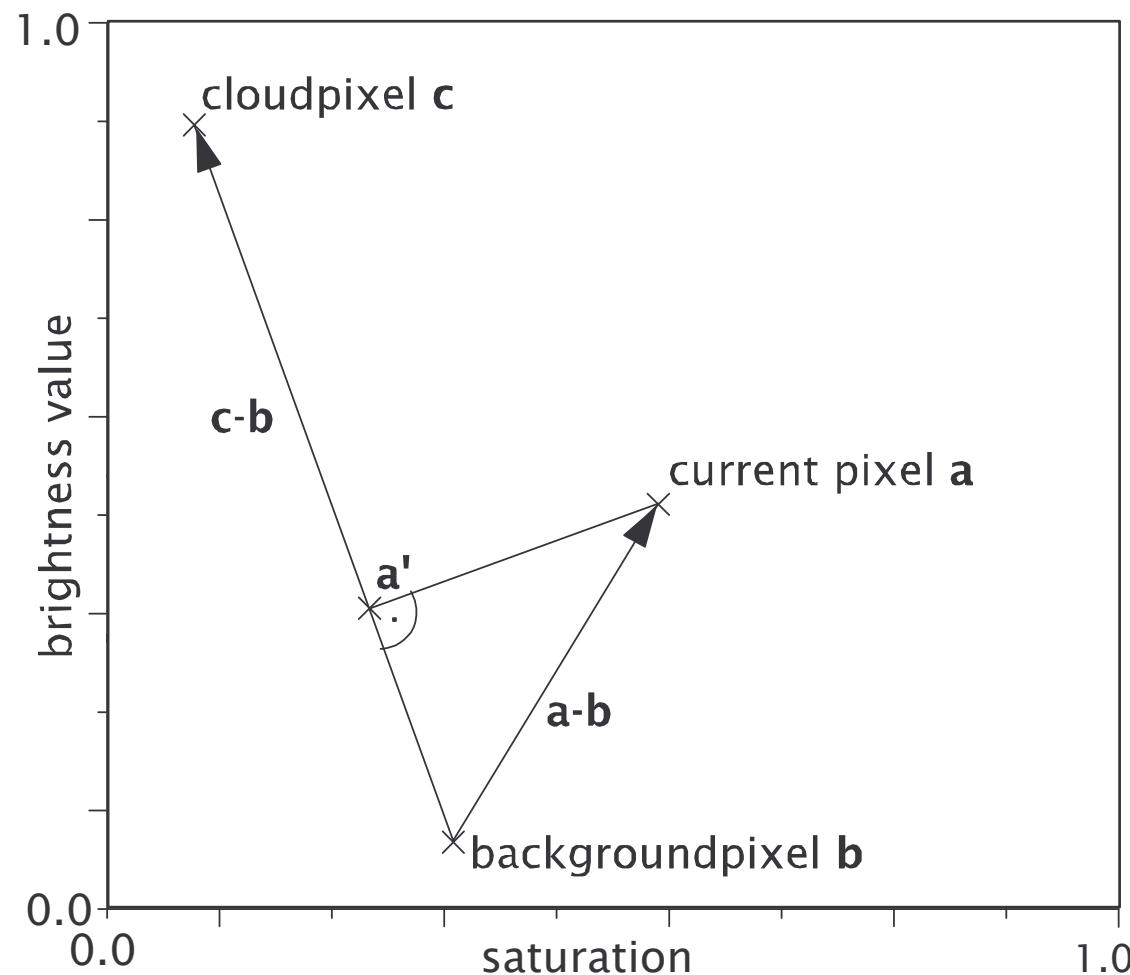
HSV and RGB colour space



CRUSA iteration



CRUSA interpolation





CRUSA 18.02.1997

