

IOMASA WP 1.2: Development of algorithms for retrieval of atmospheric parameters

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1. Total water vapor from AMSU-B
2. Surface emissivity at temperature sounding frequencies
3. Cloud liquid water



Algorithm

- Measure T_b at 3 different frequencies i, j, k at which ground emissivity ϵ_s is similar but water vapor absorption different; $\kappa_i < \kappa_j < \kappa_k$
- Then the following relation can be derived

$$\ln \eta_c = \ln \left(\frac{T_{b,i} - T_{b,j} - b_{ij}}{T_{b,j} - T_{b,k} - b_{jk}} \right) = c_0 + c_1 W \sec \theta$$

where the “bias” (b_{jk}, b_{ij})

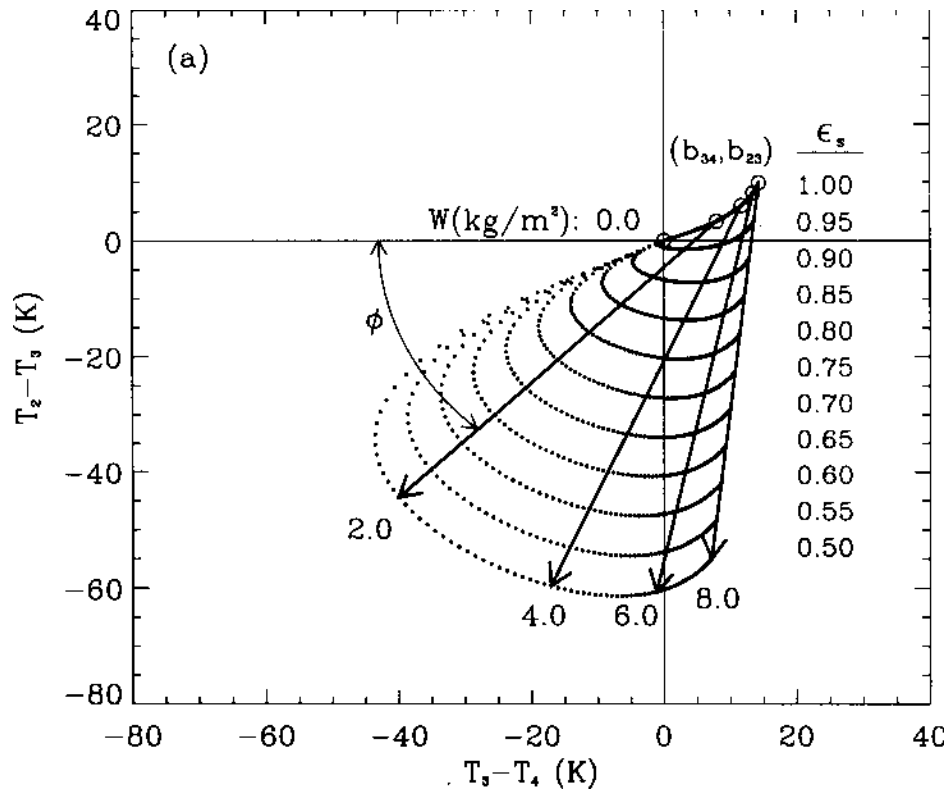
$$b_{ij} \approx \int_0^H \left[e^{\tau_i(z,H) \sec \theta} - e^{\tau_j(z,H) \sec \theta} \right] \frac{dT(z)}{dz} dz$$

contains the influence of the atmospheric temperature and water vapor profiles

AMSU-B channels (sorted so that $\kappa_2 < \kappa_3 < \kappa_4 < \kappa_5$)

our no.	1	2	3	4	5
Freq. [GHz]	89.0	150.0	182.31±7	182.31±3	182.31±1
AMSU channel	16	17	20	19	18





$$TWV = \left(C_0 + C_1 \log \frac{T_{b,i} - T_{b,j} - F_{ij}}{T_{b,j} - T_{b,k} - F_{jk}} \right) \cos \theta$$

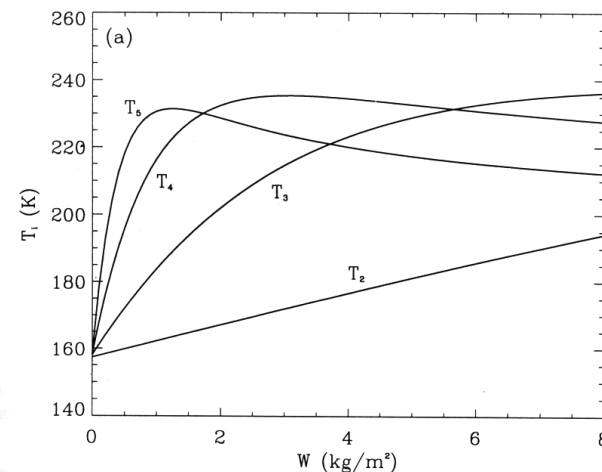
\Rightarrow 4 calibration parameters: C_0, C_1, F_{ij}, F_{jk}

Note: (b_{jk}, b_{ij}) slightly dependent on T and W profile
 \Rightarrow find some kind of average $(F_{jk}, F_{ij}) = (\overline{b_{jk}}, \overline{b_{ij}})$ (focal point)



Algorithm Development for AMSU-B

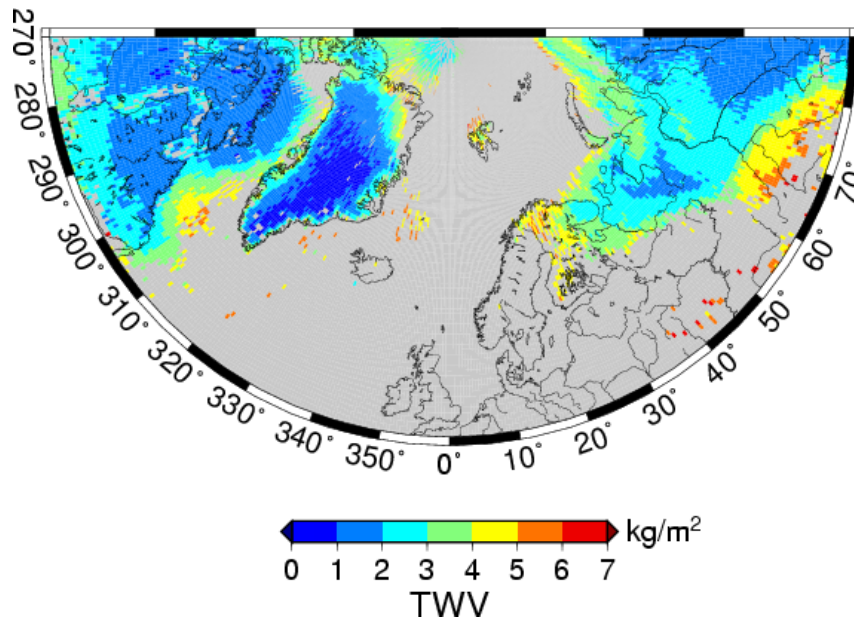
- Use **radiosonde** (RS) profiles, **integrate TWV** from them and **simulate AMSU-B** brightness temperatures T_1, T_2, T_3, T_4, T_5 for a range of ground emissivities ϵ_s for each RS profile
 - Several **regressions** yield the **calibration parameters** C_0, C_1, F_{ij}, F_{jk}
 - **Two separate sets** of calibration parameters, one for $(i, j, k) = (2, 3, 4)$ (“**234-algorithm**”), one for $(i, j, k) = (3, 4, 5)$ (“**345-algorithm**”)
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- $T_4 - T_5 < 0$ (low TWV) → use **345-algorithm**
 - $T_4 - T_5 > 0$ (but still $T_3 - T_4 < 0$, $T_2 - T_3 < 0$) → use **234-algorithm**;
 - $T_3 - T_4 > 0$ (high TWV , $> 6 \text{ kg/m}^2$) → no algorithm (yet)



Current Status

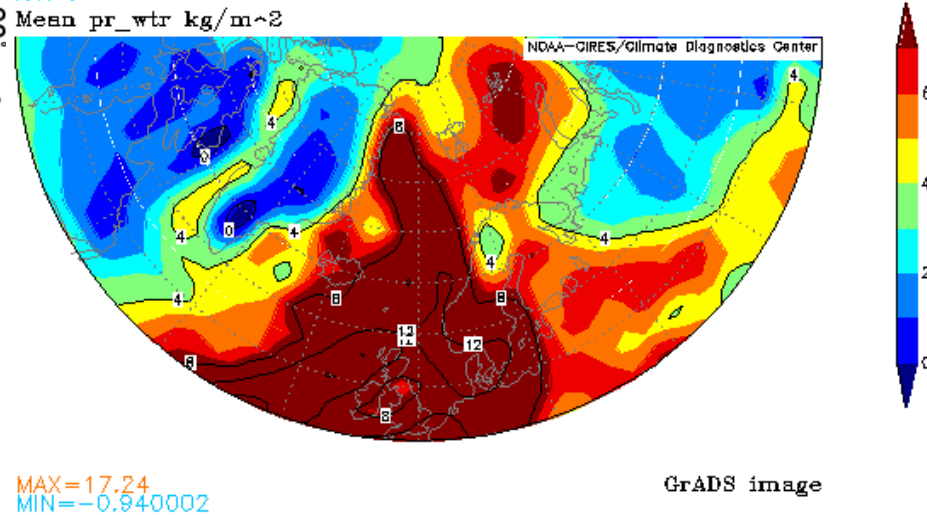
- Calibration parameters can be derived for
 - given *TWV range* of RS data (necessary)
 - *regional* subset of RS data (station IDs)
 - *seasonal* subset of RS data (date range regardless of year)
 - *temporal* subset of RS data (date range including year)
 - any *combination* thereof
- *TWV maps* or *grid files* can be calculated for AMSU-B swath data using any calibration parameter files (from above); gridding and mapping using GMT
 - one or several *swaths*
 - *daily average* (all swaths for one day)

Results



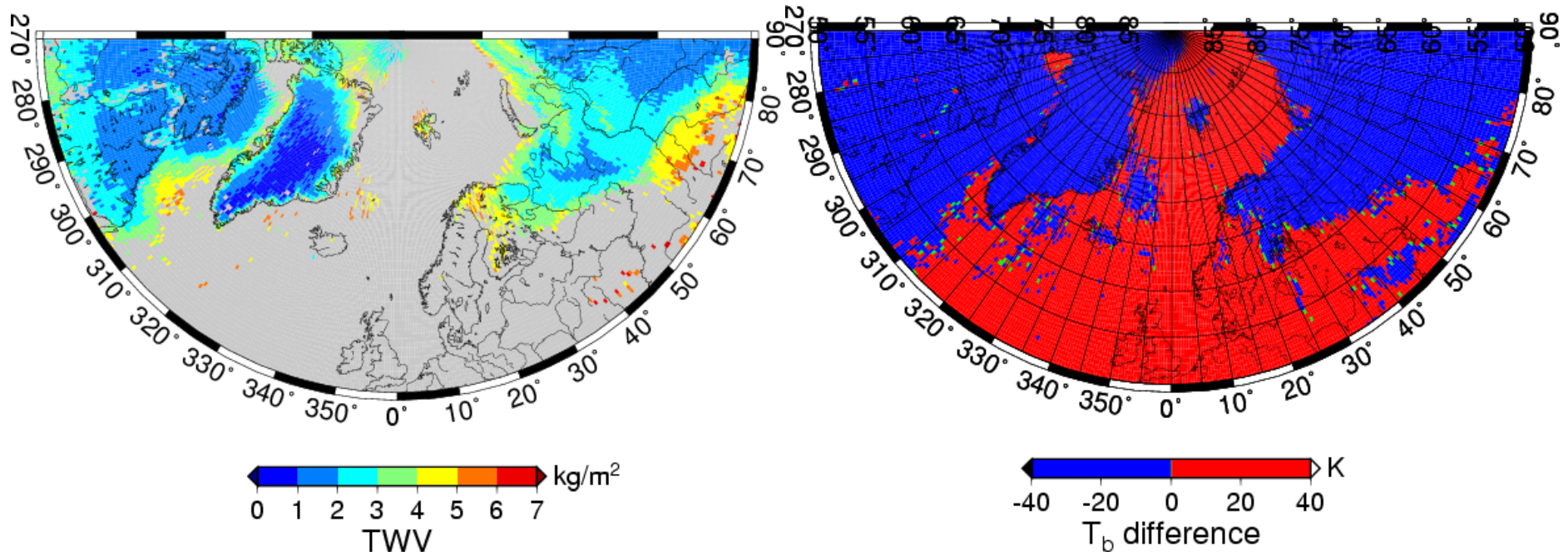
TWV, 1 January, 2000

lon: plotted from -90 to 90.0
lat: plotted from 50.00 to 90.00
t: Jan 1 2000
lev: 0



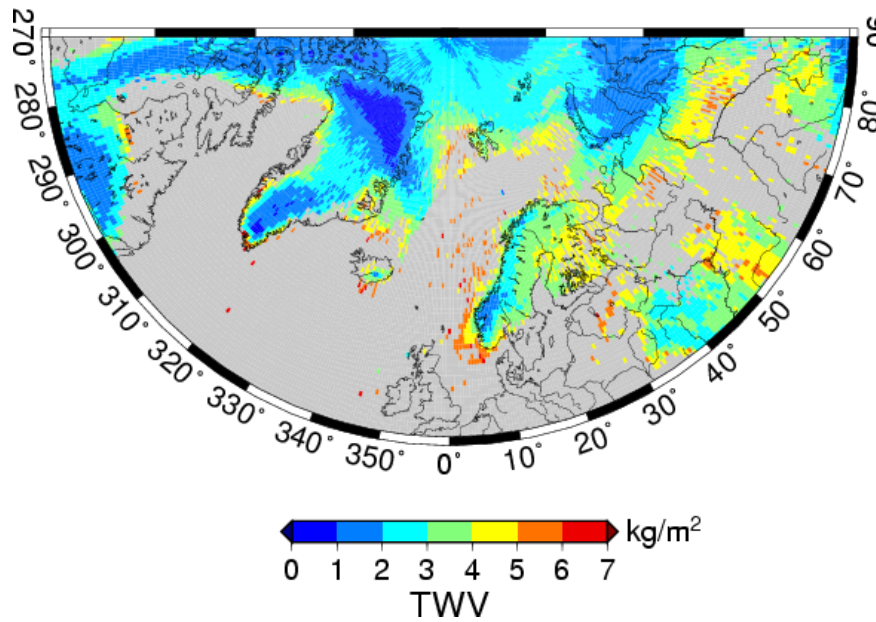
NCEP reanalysis data, same day





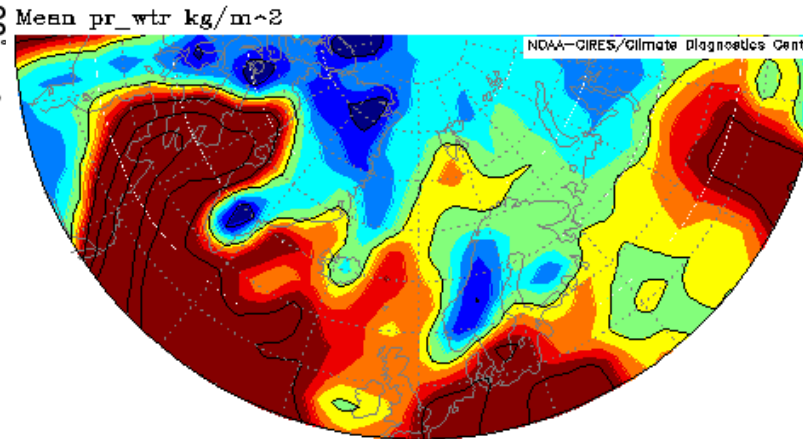
TWV, 1 January, 2000

Brightness temperature difference $T_3 - T_4$



TWV, 1 March, 2001

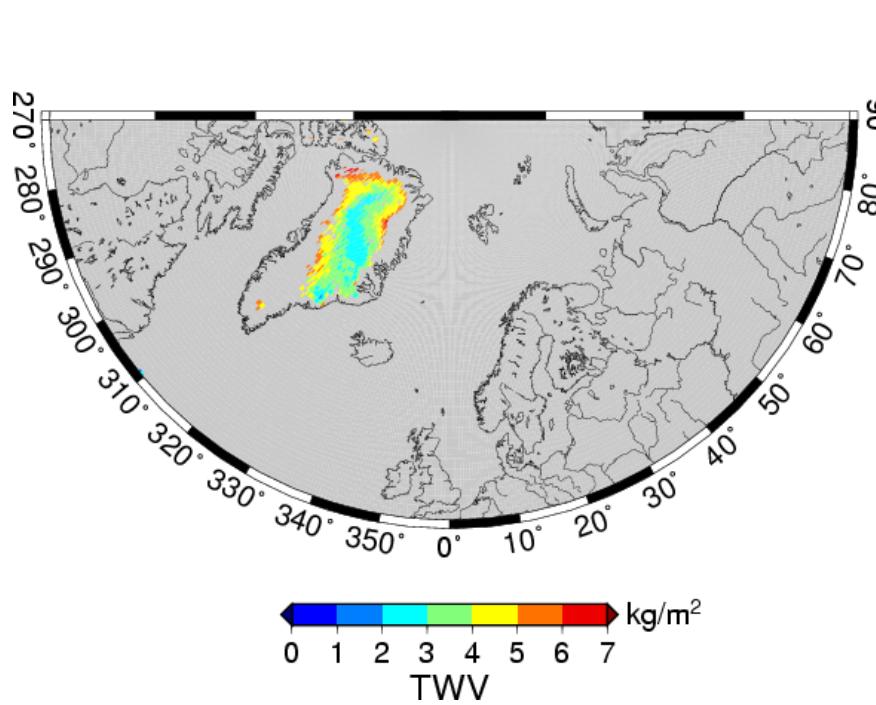
lon: plotted from -90 to 90
lat: plotted from 50 to 90.00
t: Mar 1 2001
lev: 0



MAX=19.82
MIN=-1.31

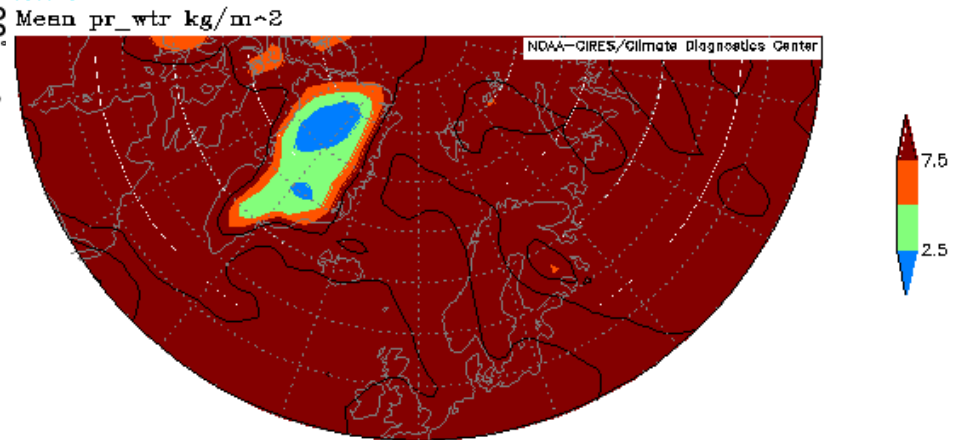
GrADS image

NCEP reanalysis data, same day



TWV, 28 August, 2001

lon: plotted from -90 to 90
lat: plotted from 50 to 90.00
t: Aug 28 2001
lev: 0

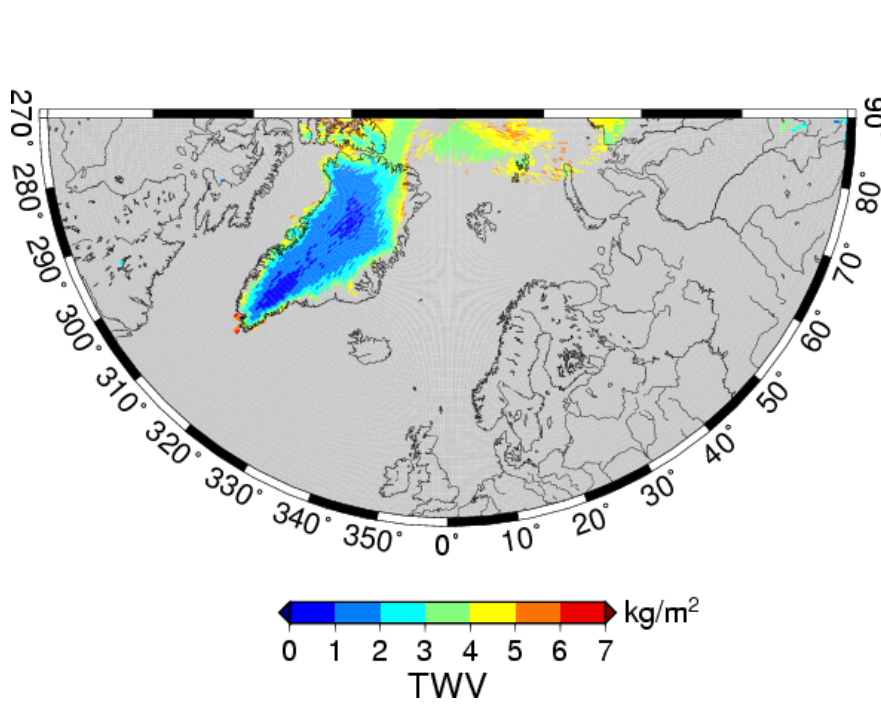


MAX=40.59
MIN=0.839996

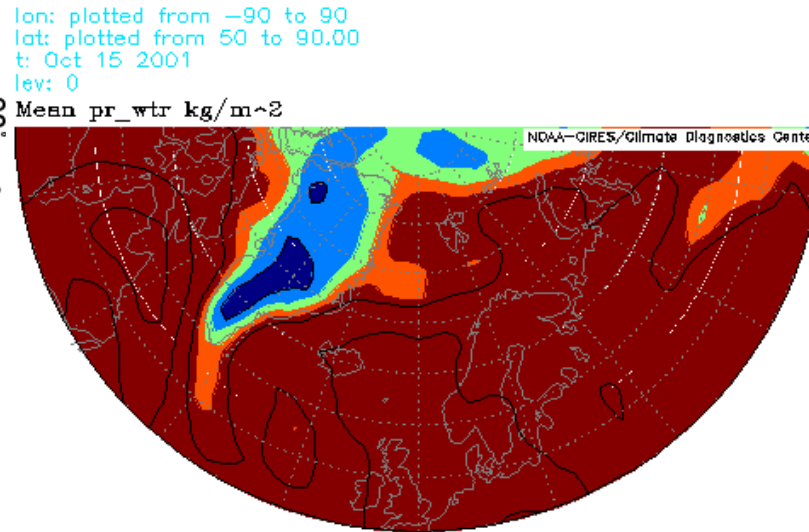
GrADS image

NCEP reanalysis data, same day





TWV, 15 October, 2001



MAX=36.09
MIN=-1.41

GrADS image

NCEP reanalysis data, same day



Results: Saturation Cut-Off

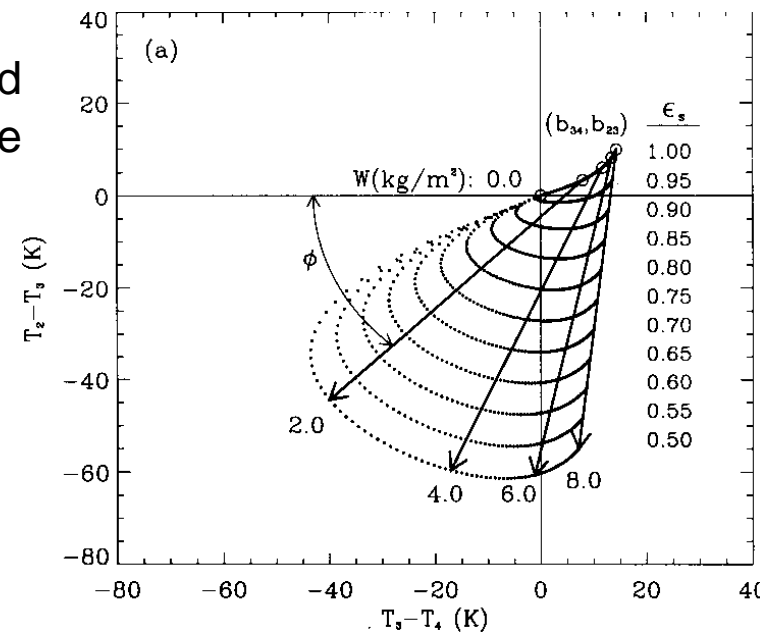
- Condition when algorithm is not applied any more (saturation) is $T_3 - T_4 \geq 0$, the critical value (“saturation cut-off”) $S = 0$

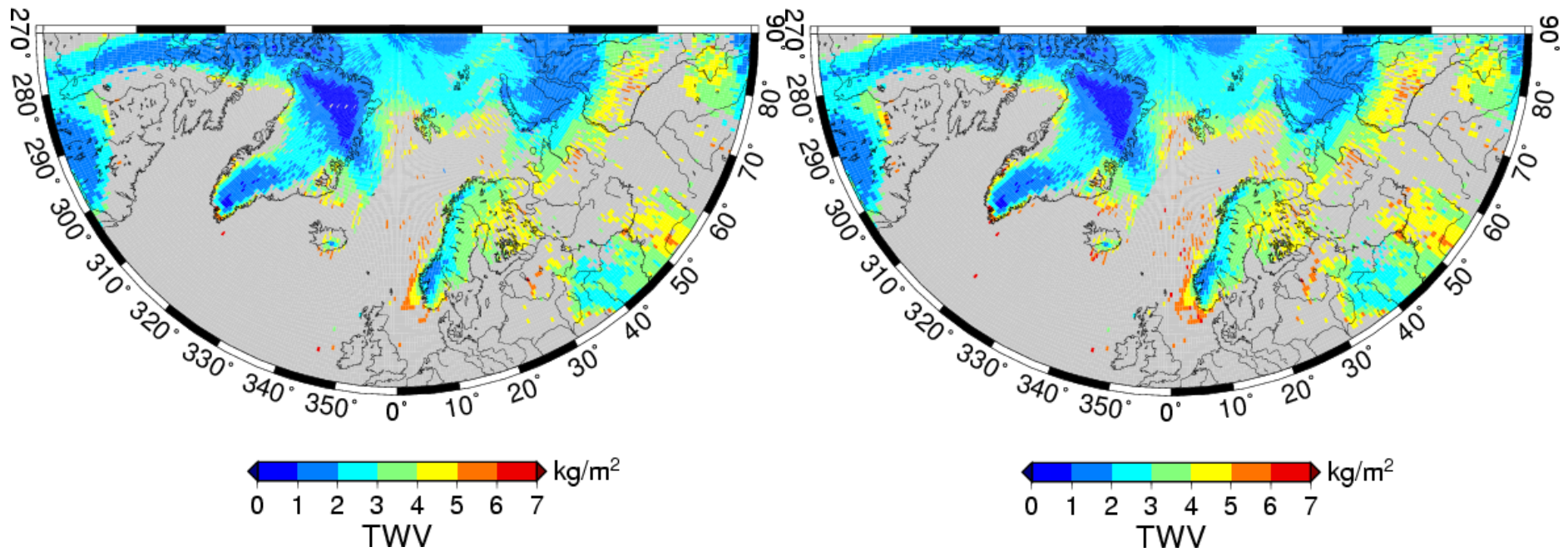
but the focal point coordinates are positive, order of a few K

?? Can we push the saturation cut-off towards positive values?

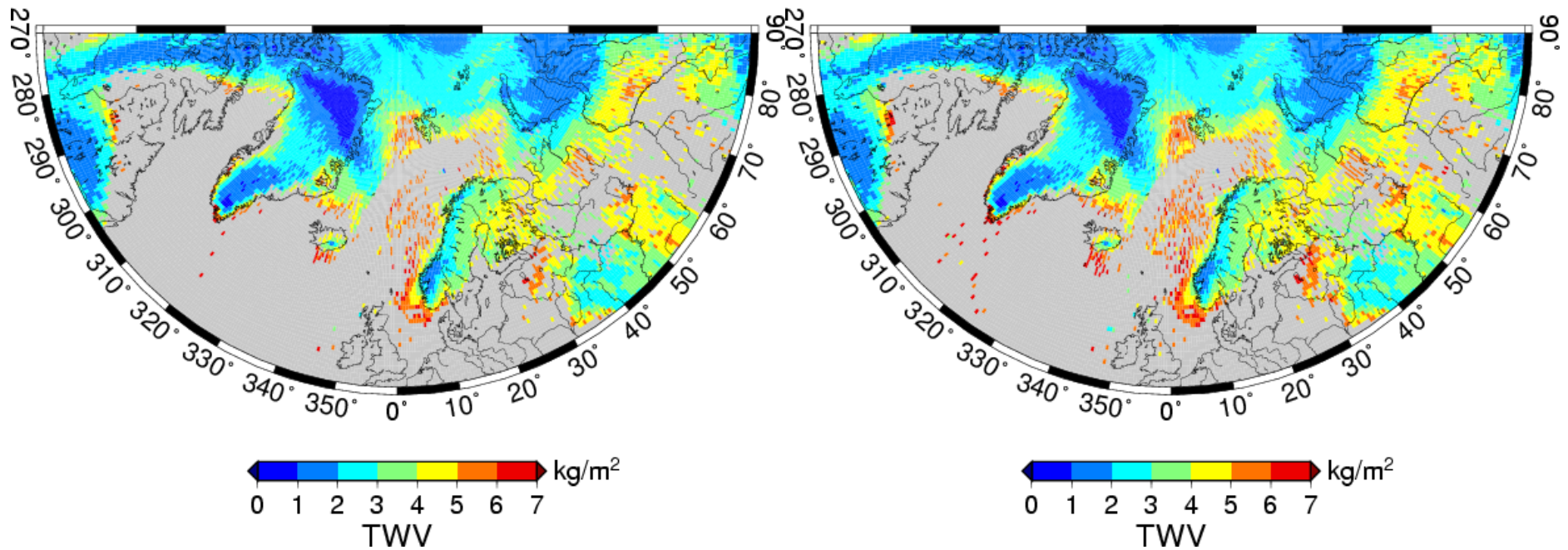
- As long as both numerator and denominator of the log argument are negative, the algorithm should work.

$$\log \frac{T_{b,i} - T_{b,j} - F_{ij}}{T_{b,j} - T_{b,k} - F_{jk}}$$



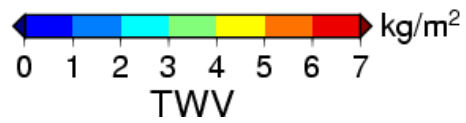
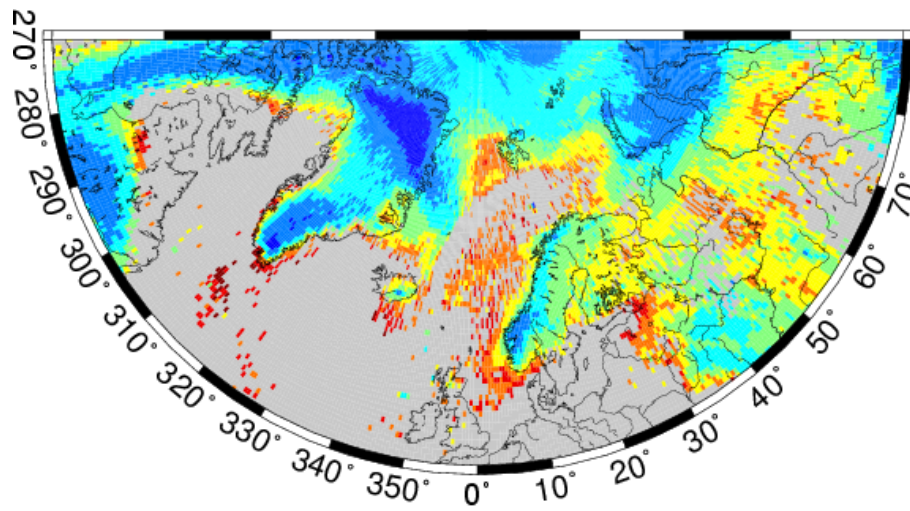


TWV, 1 March, 2001: Saturation cut-off $S = 0$ as before, but $S = 1$

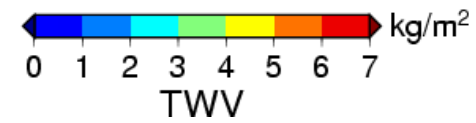
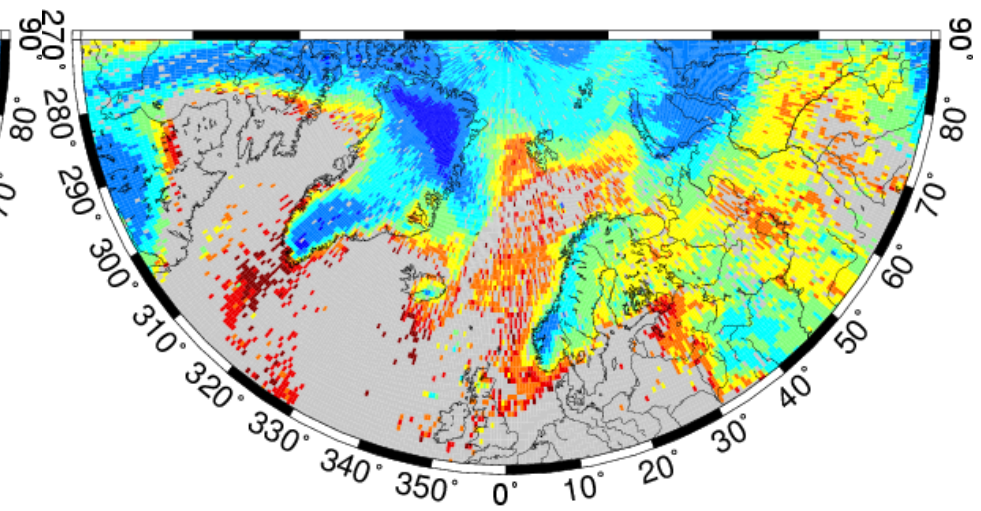


as before, but $S = 2$

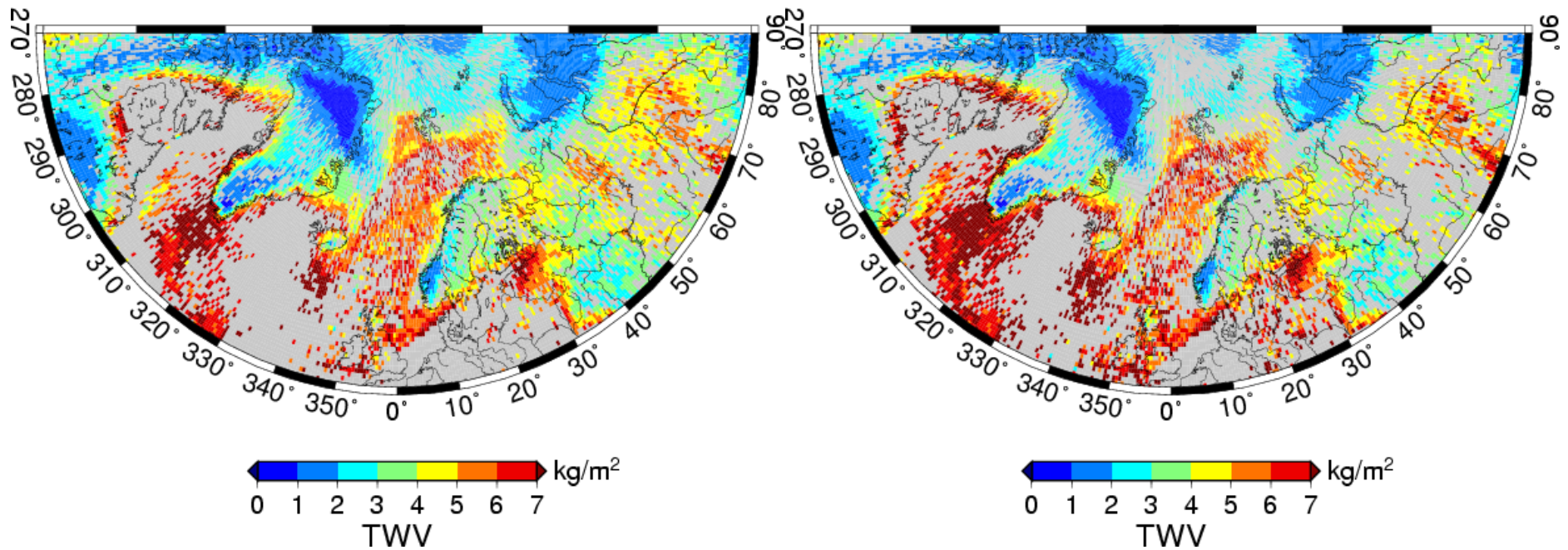
as before, but $S = 3$



as before, but $S = 4$

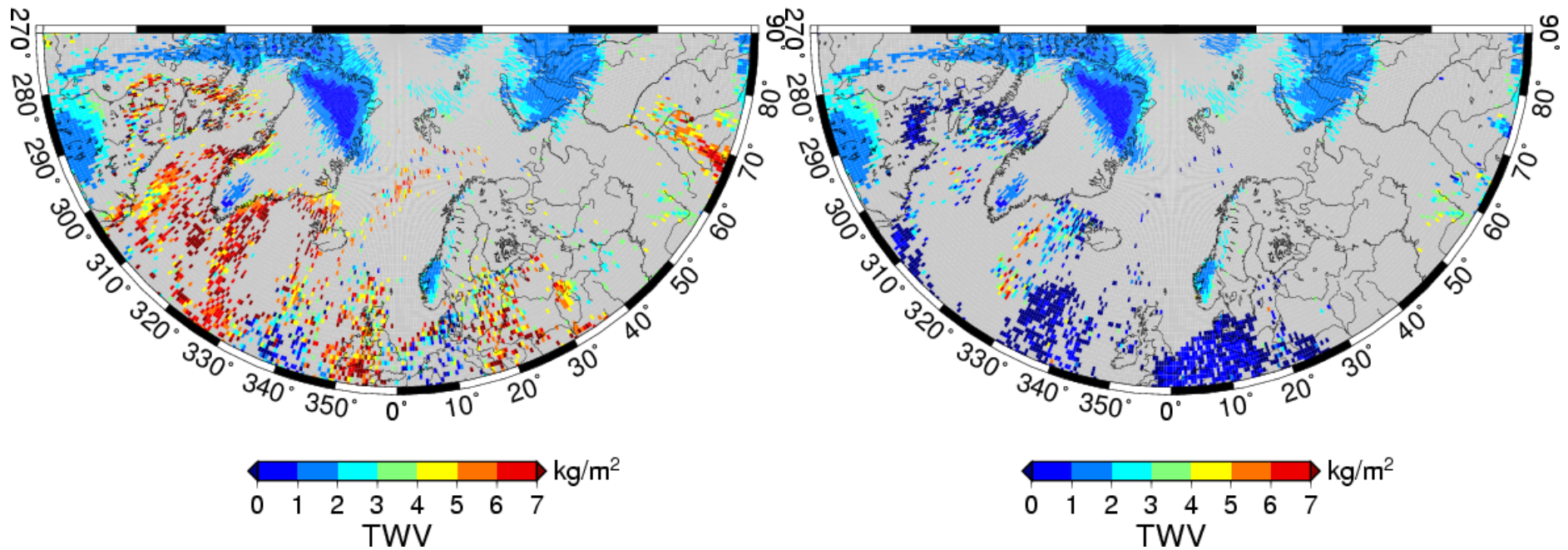


as before, but $S = 5$



as before, but $S = 6$

as before, but $S = 7$



as before, but $S = 10$

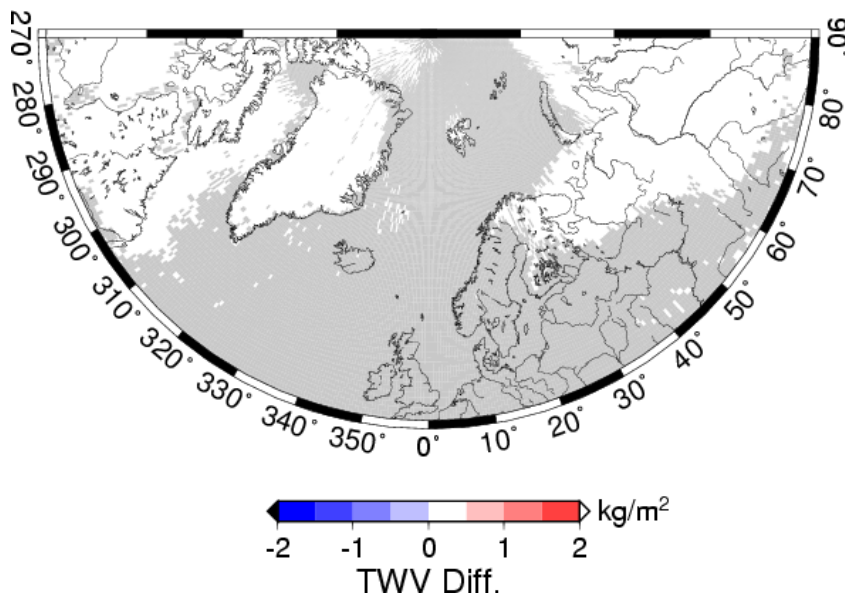
as before, but $S = 15$

Seasonal calibration parameters

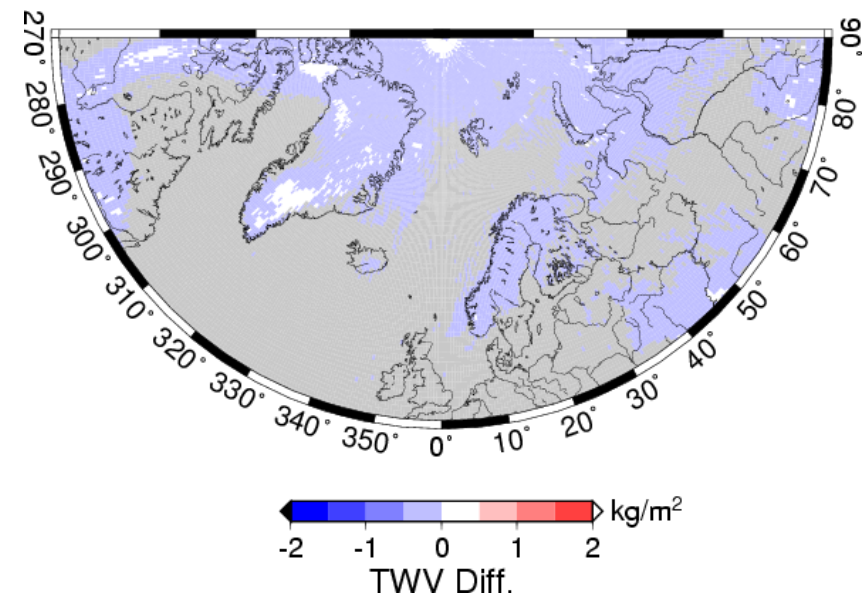
Calibration parameters from RS data from **all year round**

vs.

Calibration parameters from RS data from **one month**



TWV with calibr. parameters whole year
minus TWV with calibr. parameters
January: 1 Jan 2000



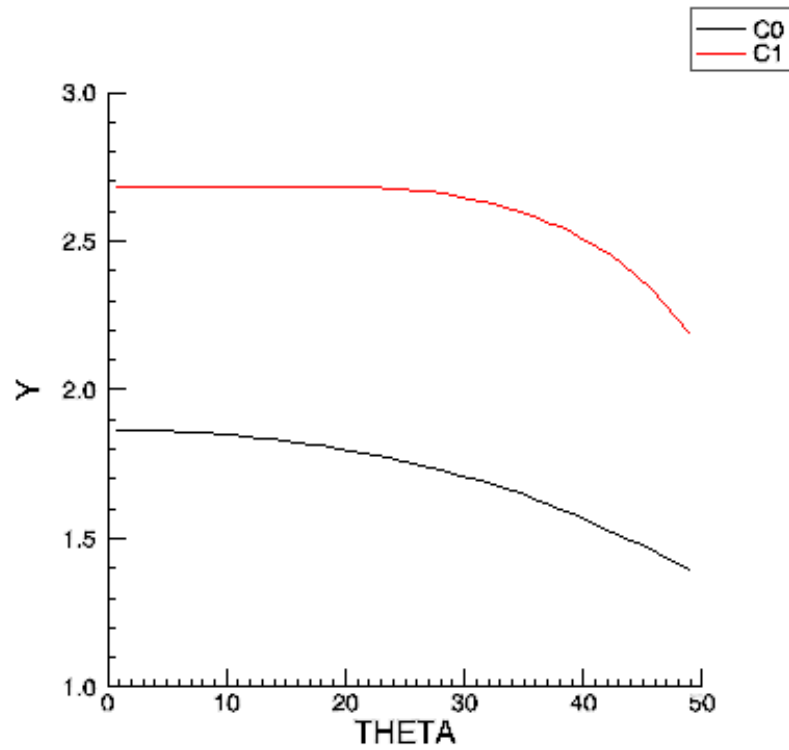
TWV with calibr. parameters whole year
minus TWV with calibr. parameters
March: 1 Mar 2001

Dependence of calibration parameters on scan angle

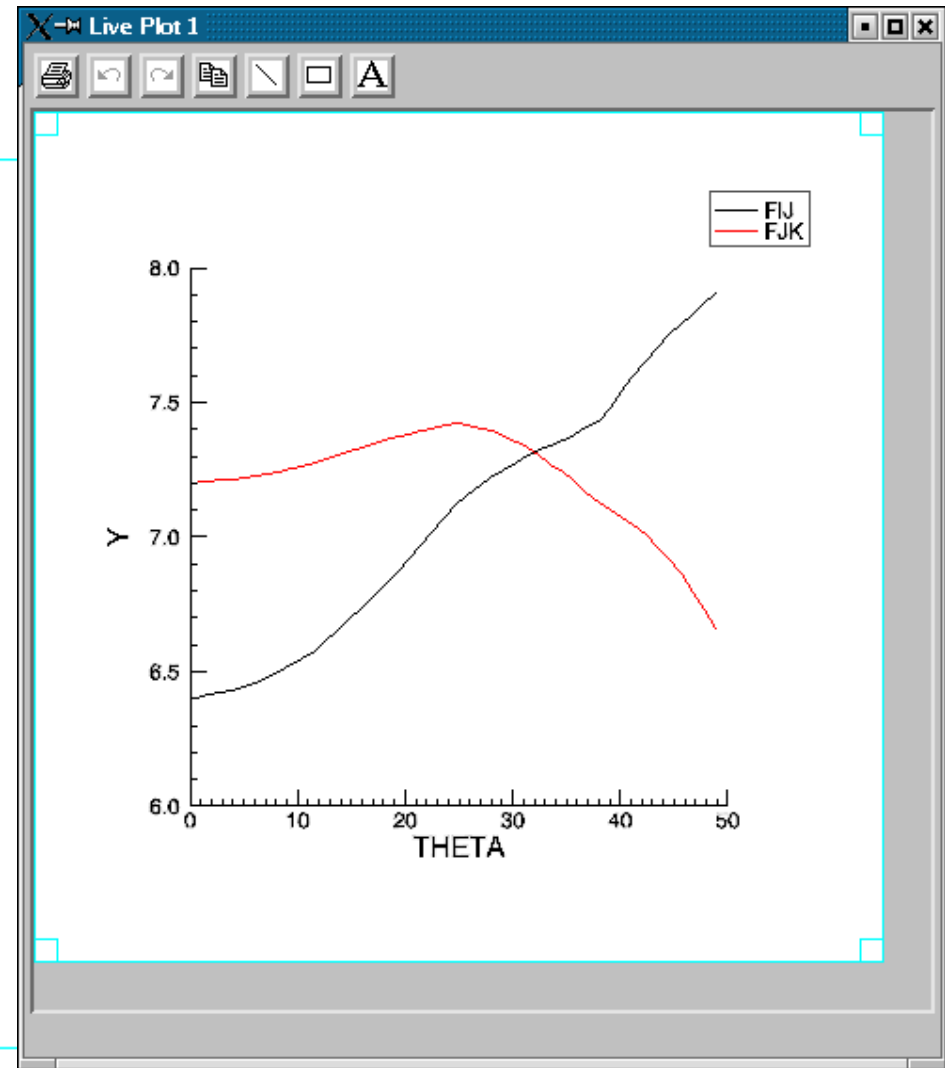
- Bias terms b_{ij} , b_{jk} depend on scan angle (incidence/zenith/looking angle) in complicated way – not just by the path length factor $\sec \theta$:

$$b_{ij} \approx \int_0^H \left[e^{\tau_i(z,H) \sec \theta} - e^{\tau_j(z,H) \sec \theta} \right] \frac{dT(z)}{dz} dz$$

- Calibration parameters were derived and applied for each scan angle (incidence/zenith/looking angle) separately

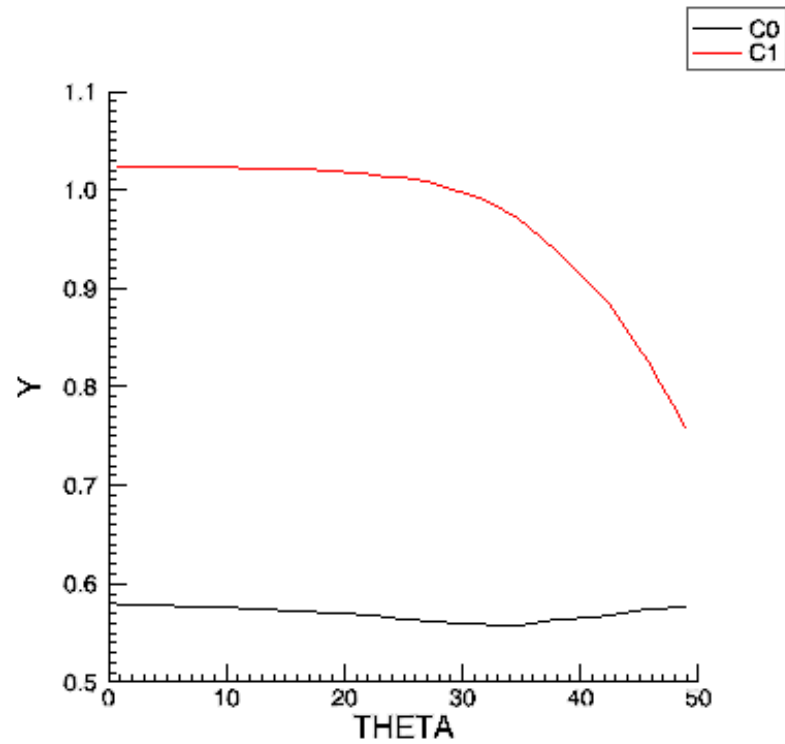


Constants C_0 , C_1 for 234-algorithm

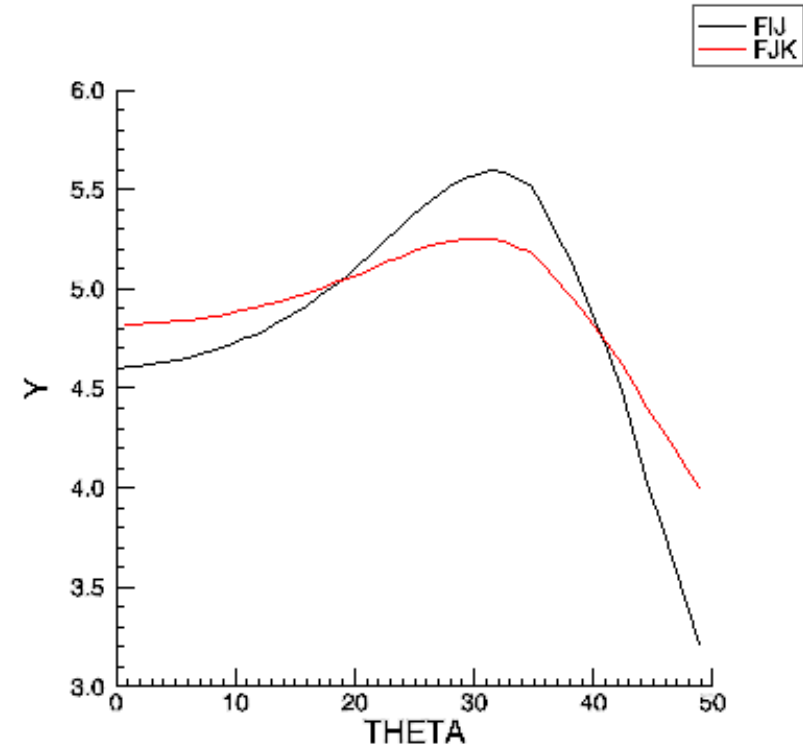


Focal point coordinates for 234-algorithm





Constants C_0, C_1 for 345-algorithm



Focal point coordinates for 345-algorithm

Ongoing Work, Ideas

- Implement **sub-ranges**, two-step algorithm:
 - Derive calibration constants for TWV sub-ranges $[0, 0.5]$, $[0.5, 1.0]$, $[1.0, 1.5]$, etc.
 - calculate TWV once, using simple 234-/345-algorithm
 - Based on the resulting TWV values, apply the algorithms derived for the matching sub-range.
- Investigate **seasonal variations** of calibration parameters
- **Gridding/interpolation** issues
- Optimize the **saturation cut-off** (link to focal point coordinates, i.e., 2 values for each algorithm?)
- Estimate **error** (mainly from **fuzziness** of **focal point**?)
- More **validation** besides NCEP data; other sensors